MATH 54 - HINTS TO HOMEWORK 5

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Here are a couple of hints to Homework 5! Enjoy! :)

SECTION 4.4: COORDINATE SYSTEMS

Remember: It's easier to figure out x once we know $[x]_{\mathcal{B}}$ than the reverse. Also, remember that the change of coordinates matrix is just the matrix whose columns are the elements in \mathcal{B} .

It takes a code as its input and tells you which vector corresponds to that code. Its inverse matrix does what you usually want: It produces the coordinates of x

4.4.27. Use the basis $\mathcal{B} = \{1, t, t^2, t^3\}$, and compute the coordinates of the 4 polynomials. Then the polynomials are linearly independent if and only if their corresponding vectors are linearly independent!

SECTION 4.5: THE DIMENSION OF A VECTOR SPACE

4.5.1, **4.5.3**, **4.5.7**, **4.5.9**. First express the subspace as the span of some vectors, and then use the following useful trick:

Useful trick: To find a basis of a collection of vectors, form the matrix A whose columns are the vectors, and all you need to do is to find a basis for Col(A). In particular, the dimension of the subspace is the dimension of Col(A) (which is the number of pivots).

4.5.26. I did this on Friday! Suppose $\mathcal{B} = {\mathbf{v_1}, \mathbf{v_2}, \cdots \mathbf{v_n}}$ is a basis for *H*. What two things can you say about \mathcal{B} ? Then use the Basis theorem (Theorem 12).

4.5.27. Find an infinite linearly independent set in \mathbb{P} . For example, $\{1, x, x^2 \cdots\}$ works!

SECTION 4.6: THE RANK OF A MATRIX

Remember that the rank of A is just dim(Col(A)). It is also equal to dim(Row(A)) and to $Rank(A^T)$ and to the number of pivots of A.

4.6.7, 4.6.9, 4.6.11, 4.6.13, 4.6.15. Use the equation dim(Nul(A)) + Rank(A) = n. Also, rank(A) is largest when Nul(A) is smallest.

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4.6.17.

- (a) T
 (b) F
 (c) T
- (d) **F**
- (e) **F**

4.6.23. This question is just meant to confuse you with words! All that it says is if dim(Nul(A)) = 2 and n = 8, then what is Row(A)?

4.6.33. I urge you to do 4.6.32 before, it makes this much easier! The point is that if A has rank 1, then all its columns are multiples of the first column. In particular, let v be the

list of the coefficients. For example, if $A = \begin{bmatrix} 1 & -3 & 4 \\ 2 & -6 & 8 \end{bmatrix}$, then let $\mathbf{v} = \begin{bmatrix} 1 \\ -3 \\ 4 \end{bmatrix}$, because

the second column is -3 times the first one and the third column is 4 times the first one.

If the first column of A is zero, try the second column. If the second column is zero, try the third column. If neither of those hold, then A is the zero matrix, which does not have rank 1.

SECTION 4.7: CHANGE OF BASIS

Remember: To change coordinates from \mathcal{B} to \mathcal{C} , just express the vectors in \mathcal{B} in terms of the vectors in \mathcal{C}

4.7.33. (*ii*), because P is just $\mathcal{W} \leftarrow^{P} \mathcal{U}$, so P goes from \mathcal{U} to \mathcal{V} .

4.7.11.

- (a) **F**
- (b) **T**

4.7.17. IGNORE! But if you do 4.7.17 and 4.7.18, you'll have a completely different and awesome view of calculus and linear algebra!